

Prognostics based on the Fokker-Planck Equation

Reliability and RUL from Physical Models

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This Presentation



■ Motivation

- Prognostics: important part of predictive (smart) maintenance
- Easy-to-use (commercial) Multiphysics simulation tools for nonlinear partial differential equations exist

☐ Content

- Modeling aging/degradation with stochastic differential equations and the Fokker-Planck equation
- Reliability and Remaining Useful Lifetime (RUL)
- Correction steps update with new information (e.g., from diagnostics)
- Examples and applicability extensions
 - Brownian motion with drift
 - Auxiliary variables
 - Variable failure boundaries
 - Chance failures in addition to wear-out failures

Ref.: T. C. and F. Macedo, "Theory of Fokker-Planck Equations for Reliability and Remaining Useful Lifetime Prognostics", accepted by IEEE Transactions on Reliability, 2023

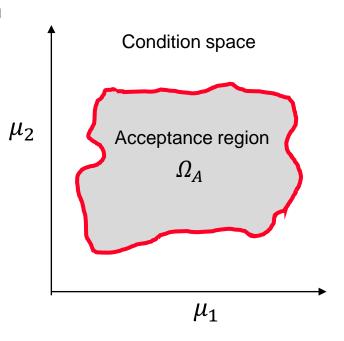
Device Model Variables and Parameters, and Condition Space



- \square Time dependent state variable $\vec{\phi} \in \text{State Space } (\underline{\text{continuous}} \text{ time } t)$
- \square Device model parameters $\vec{\mu}^{(D)} \in \text{Parameter Space } \Omega$ (Condition Space)
- $oldsymbol{\square}$ Device operations represented by solutions $ec{\phi}_{ec{\mu}^{(D)}}(t)$ of dynamical system

$$\frac{d\vec{\phi}}{dt} = \vec{F}_{\phi}(\vec{\phi}, \vec{\mu}^{(D)}, t)$$

- figspace Malfunction/failure \equiv inacceptable behavior $\vec{\phi}_{\overrightarrow{\mu}^{(D)}}(t)$
 - If $\vec{\mu}^{(D)} \in \Omega_A$ (Acceptance region) \rightarrow device can perform its task
 - If $\vec{\mu}^{(D)} \notin \Omega_A \rightarrow$ device fails to perform its task

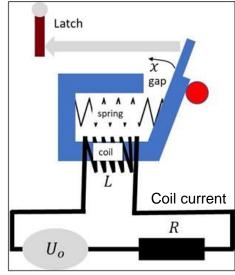


Examples



Electro-magneto-mechanical actuator





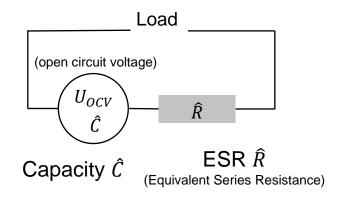
$$\vec{\phi} = \begin{pmatrix} x \\ I \end{pmatrix} = \begin{pmatrix} \text{mechanical coordinate} \\ \text{coil current} \end{pmatrix}$$

 $\mu^{(D)}$ = required inception force (spring force, static friction, ...)

Malfunction: unable to act with sufficient force and within sufficient time

Battery (other energy storage devices analogous)





 $\phi = Q$ (state of charge, SOH)

$$\vec{\mu}^{(D)} = \begin{pmatrix} \hat{\mathcal{C}} \\ \hat{R} \end{pmatrix}$$
 - or normalized wrt beginning of life: $\begin{pmatrix} \hat{\mathcal{C}}/\hat{\mathcal{C}}_{BOL} \\ \hat{R}_{BOL}/\hat{R} \end{pmatrix}$

<u>Malfunction</u>: unable to provide sufficient $\binom{\text{energy}}{\text{power}}$

Degradation and End of Life

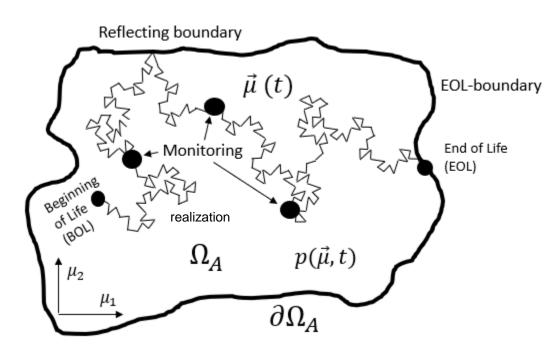


- \square Beginning of Life (BOL): initial state $\vec{\mu}(0) = \vec{\mu}_{BOL}$ of aging model variables
- \square Aging or degradation: (slow) motion $\vec{\mu}(t)$ in acceptance region
 - Deterministic part ("drift", \vec{f})
 - Stochastic part ("random walk", white noise $\vec{\xi}(t)$)

$$\frac{d\vec{\mu}}{dt} = \vec{f}(\vec{\mu}, t; \vec{\alpha}) + g(\vec{\mu}; \vec{\alpha}) \vec{\xi}(t)$$
 (Langevin equation, stochastic differential equation)

(note: aging variable space is generally larger than device model parameter space!)

- \square When boundary $\partial \Omega_A$ of acceptance region is reached:
 - Impermeable: reflecting boundaries
 - Malfunctions, End of Life (EOL): absorbing boundaries
 - ...



Langevin Equation (LE) and Fokker-Planck Equation (FPE)



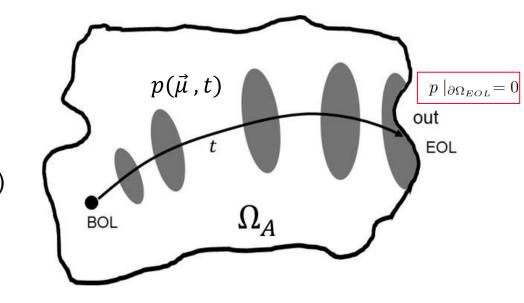
 \square FPE for probability density $p(\vec{\mu}, t)$ (individual device: "Bayesian interpretation")

$$\frac{\partial p}{\partial t} = -\nabla_{\mu} \cdot \vec{J}_{\mu} = \sum_{i} \frac{\partial}{\partial \mu_{i}} \left(\sum_{j} \frac{\partial}{\partial \mu_{j}} (D_{ij}p) - f_{i}p \right)$$

- - Diffusion matrix $(D_{ij} = D_{ij}(\boldsymbol{g}); \Delta \text{Itô/Stratonovich-dilemma}\Delta)$
 - Drift-flow velocity $\vec{f}(\vec{\mu}, t)$ (can be arbitrarily nonlinear)
- Initial condition at BOL
 - $-p(\vec{\mu},t=0)=p_{BOL}(\vec{\mu})$ (usually) normalized in Ω_A



- Reflecting/insulating boundary: vanishing normal component of \vec{j}_{μ} at boundary $\partial \Omega_A$
- Absorbing EOL boundary: p=0 at $\partial\Omega_A$
- Distribution (remains) generally not Gaussian (boundary conditions, nonlinearities, ...)



Reliability and Remaining Useful Life

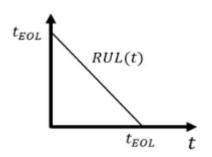


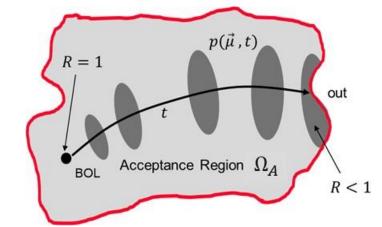
- \square Reliability from $p(\vec{\mu}, t)$
 - $R(t) = ext{survival probability} = ext{probability to be in } \Omega_A$

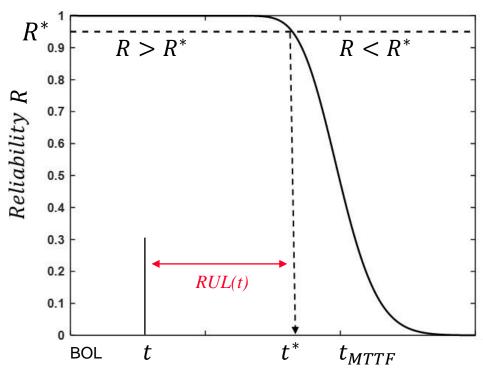
$$R(t) = \int_{\Omega_A} d\mu \, p(\vec{\mu}, t)$$

- ☐ Remaining Useful Lifetime (RUL)
 - Reliability limit R^* : device condition acceptable iff $R>R^*$
 - RUL = time until $R = R^*$

$$RUL(t) = t_{EOL} - t$$







Intermediate Information Gain: Correction Step



 \Box Up to now: <u>Prediction step:</u> $p(\vec{\mu}, t)$ calculated from FPE until (discrete) time $t_m \rightarrow$ predicted condition probability at t_m

$$p_{<}(\vec{\mu}, t_m) = \lim_{\epsilon \to 0, \epsilon > 0} p(\vec{\mu}, t_m - \epsilon)$$

 \Box Additional information gain (monitoring, diagnostics) at $t=t_m$ on $\vec{\mu}$ \to likelihood

$$p_m(\vec{\mu}, t_m)$$

Correction step

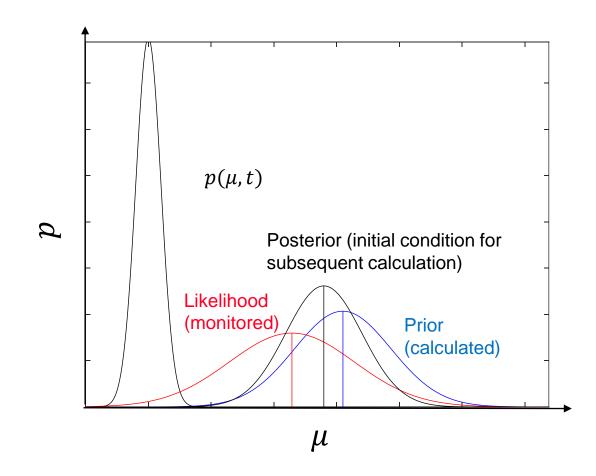
Update p with Bayesian inference

Posterior "Likelihood" prior
$$p_{>}(\vec{\mu},t_m) = C \; p_m(\vec{\mu},t_m) p_{<}(\vec{\mu},t_m)$$

Normalization constant C

☐ Continue to solve the FPE with "new initial condition"

$$p(\vec{\mu}, t)|_{t=t_m} = p_{>}(\vec{\mu}, t_m)$$



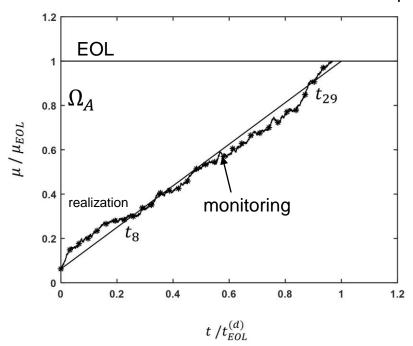
Summary for 1d Condition Variable Example, known $\vec{\alpha} = (f, D)$



☐ Aging model (Brownian motion with drift) Langevin equation ($\mu \ge 0$)

$$\frac{d\mu}{dt} = f + \sqrt{2D}\xi(t)$$

Here: simulation of stochastic differential eq.

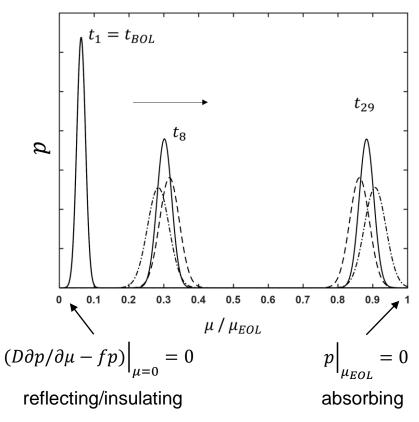


Public (d) = deterministic © 2023 Hitachi Energy. All rights reserved.

☐ Fokker-Planck equation (drift-diffusion)

$$\frac{\partial p}{\partial t} = \frac{\partial}{\partial \mu} \left(D \frac{\partial p}{\partial \mu} - f p \right)$$

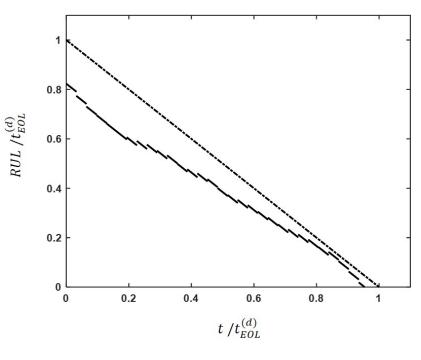
Simulation of partial differential equation



☐ Reliability and Lifetime

$$R(t) = \int_{0}^{\mu_{EOL}} d\mu \, p(\vec{\mu}, t)$$

Calculation of RUL from reliability



Auxiliary Aging Variables

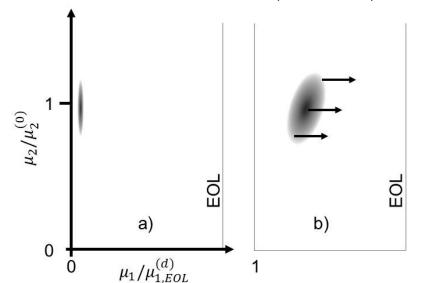


What if some of the aging model parameter values $\vec{\alpha}$ are not known or variable? \rightarrow Consider as additional stochastic variables

- \square Simple example: rate f of previous model is stochastic variable
 - f extension of aging model variable space

$$\mu_2 = f$$

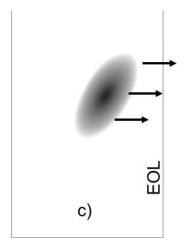
FEM Simulation (here Comsol)



□ 2 Langevin equations

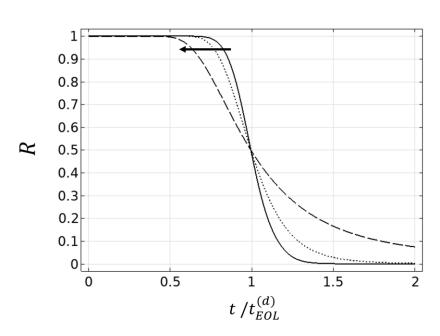
$$\frac{d\mu_1}{dt} = \mu_2 + \sqrt{2D_1}\xi_1(t)$$

$$\frac{d\mu_2}{dt} = \sqrt{2D_2}\xi_2(t)$$



☐ Fokker-Planck (2d, in rectangle)

$$\frac{\partial p}{\partial t} = \frac{\partial}{\partial \mu_1} \left(D_1 \frac{\partial p}{\partial \mu_1} - \mu_2 p \right) + \frac{\partial}{\partial \mu_2} \left(D_2 \frac{\partial p}{\partial \mu_2} \right).$$



Early arrival by higher velocity tail leads to decrease of reliability before mean time to failure

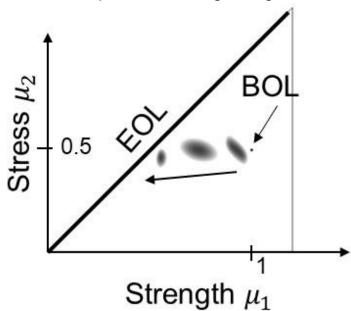
Variable Failure Boundaries and Stress-Strength Reliability



What if μ_{EOL} is variable? \rightarrow Consider strength as additional stochastic aging model variable

- Example: stress-strength reliability
 - strength μ_1
 - stress μ_2

Stress dependent strength degradation



Langevin equations

$$\frac{d\mu_1}{dt} = f_1(\mu_1, \mu_2) + \sqrt{2D_1}\xi_1(t)$$

$$\frac{d\mu_1}{dt} = f_1(\mu_1, \mu_2) + \sqrt{2D_1}\xi_1(t)$$

$$\frac{d\mu_2}{dt} = f_2(\mu_1, \mu_2) + \sqrt{2D_2}\xi_2(t)$$

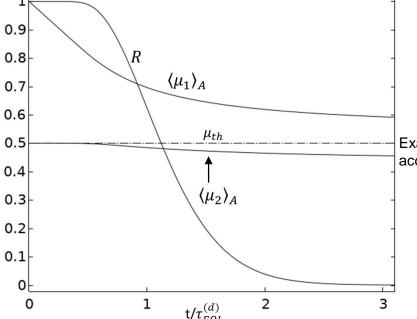
Fokker-Planck (Ω_A = triangle)

$$\frac{\partial p}{\partial t} = \sum_{k=1}^{2} \frac{\partial}{\partial \mu_{k}} \left(\frac{\partial (D_{k}p)}{\partial \mu_{k}} - f_{k}p \right).$$

Acceptance region averages

$$\langle y \rangle_A = \frac{1}{R} \int_{\Omega_A} y(\vec{\mu}) p \, d\mu$$

Example with a degradation acceleration threshold μ_{rb}



FEM Simulation (Comsol)

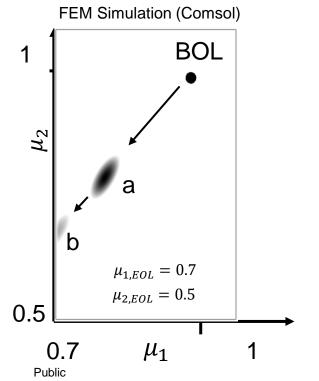
Including Chance Failures and Correlation



What if chance failures (statistical failures during useful life) need to be included in addition to wear-out (degradation) failures?
→ generalize FTE by adding sink term (→ decay rate, hazard)

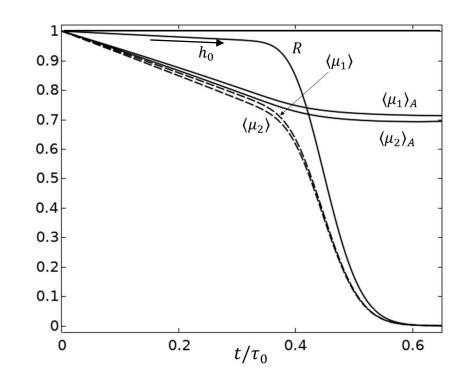
■ Example: Battery Aging

- \circ Normalized capacity μ_1
- o Normalized inverse ESR μ_2



☐ Langevin equations with nondiagonal *g*)

$$\begin{split} \frac{d\mu_1}{dt} &= f_1(\mu_1, \mu_2) + \sqrt{2D_1} \xi_1(t) \\ \frac{d\mu_2}{dt} &= f_2(\mu_1, \mu_2) + \sqrt{2D_2} \xi_2(t) + \gamma \sqrt{2D_1} \xi_1(t) \end{split}$$



☐ Fokker-Planck with sink (in rectangle)

$$\frac{\partial p}{\partial t} = \sum_{i=1}^{2} \frac{\partial}{\partial \mu_{i}} \left(\sum_{j=1}^{2} \frac{\partial}{\partial \mu_{j}} (D_{ij}p) - f_{i}p \right) - h_{0}p$$

Local conservation law as before, decay rate now with γ –dependent cross diffusion hazard h_0 (non-diagonal diffusion matrix)

Acceptance region averages

$$\langle y \rangle_A = \frac{1}{R} \int_{\Omega_A} y(\vec{\mu}) p \, d\mu$$

Acceptance region integrals

$$\langle y \rangle = \int_{\Omega_A} y(\vec{\mu}) p \, d\mu$$



Summary and Conclusion



- ☐ Convenient framework for prognostics: Fokker-Planck Equation (FPE)
- □ Prediction step
 - Degradation modeling with Langevin Equation (deterministic and stochastic part)
 - End of Life (EOL) boundaries in acceptance region of aging model variable space (or condition space)
 - FPE solved for probability distribution in acceptance region with absorbing EOL boundary conditions
 - Reliability calculated by integration of probability density in acceptance region
 - Determination of remaining useful life (RUL) from prescribed reliability limit value
- □ Correction step
 - Update probabilities with Bayesian inference when additional information is obtained
- Extensions

• Additional auxiliary stochastic aging variables can be introduced (e.g., variable failure thresholds, colored noise, ...)

- Chance failures can be modeled with a sink term in the FPE
- ☐ For dimension ≤ 3 standard commercial PDE simulation tools (here Comsol, Finite Element Method) can be used for arbitrarily coupled and nonlinear aging models.



(not discussed in this presentation)

T. C. and F. Macedo: "Theory of Fokker-Planck Equations for Reliability and Remaining Useful Lifetime Prognostics", accepted by IEEE Transactions on Reliability, 2023



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